

Local CDM ESD Protection Circuits for Cross-Power Domains in 3D IC Applications

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Abstract—CDM ESD events can be a potential threat to SoC designs or heterogeneous 3D ICs with multiple power domains. Inter-layer (or interface) circuits may need a local CDM ESD clamp that can prevent the unexpected failure under CDM ESD stress. In this letter, two local CDM ESD clamp circuits are proposed. They show better clamping efficiency under 2-ns vFTLP stress.

Index Terms—Electrostatic discharge (ESD), charged device model (CDM), cross-power domains ESD events, 3D stacked ICs, vary-fast transmission line pulsing (vFTLP) systems.

I. INTRODUCTION

Due to the increasing requirements for heterogeneous integration in state-of-the-art applications, more advanced and beneficial methodologies, such as system in a chip (SiC) with 3D vertical integrations, have been proposed in recent years. Such chips, referred to as 3D ICs, are specifically integrated with different physically separated dies connected by miniature vertical metallization structures which can be Through-Silicon-Via (TSV) [1], micro solder bump bonding [2], and so on. Multi-functional blocks are integrated in a SiC and usually possess their individual power/ground supplies for circuit performance requirements and noise coupling prevention. In a heterogeneous 3D integration system, multi-power-domain Electrostatic Discharge (ESD) protection will become a challenge [3], [4], especially for CDM ESD events [5]. Due to the very short rise time and huge amplitude of the CDM ESD peak current, the thin gate oxide of internal transistors can be easily damaged during CDM ESD events. An additional ESD clamp device, such as a gate-grounded NMOS (GGNMOS) [5], is locally added to limit the overvoltage across the internal gate oxide. However, GGNMOS cannot provide an efficient protection of thin gate oxide in nano-scale CMOS IC products, because of its higher trigger voltage under negative CDM ESD stress [6]–[9].

In this work, two CDM ESD protection designs are proposed. With simple trigger circuits, the trigger voltage can be reduced and the turn-on uniformity can be improved. In Sections II and III, the proposed designs are compared with the prior art to show its benefits in 3D IC multi-power-domain applications. Detailed circuit operations of the proposed designs are included in Section III. Section IV shows the verifications of the proposed designs by vFTLP stress. Finally, this abstract closes with the conclusions.

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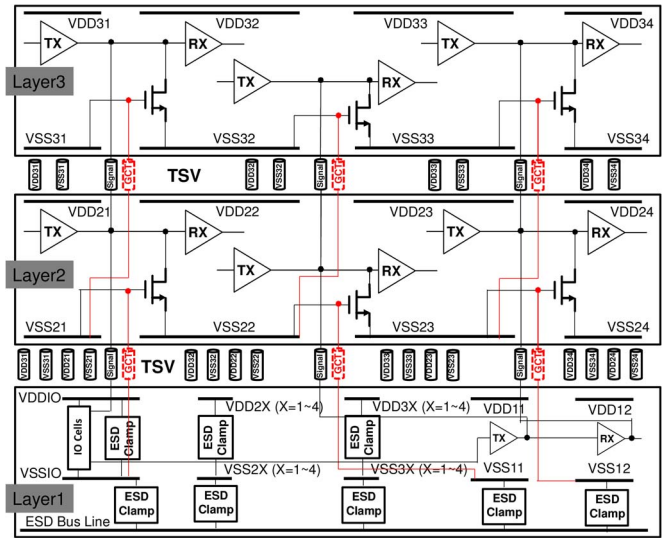


Fig. 1. Schematic illustration of 3D IC applications with the ground current trigger (GCT) technique which needs an external control signal from a different power domain or even from a different layer.

II. ACTIVE CDM ESD CLAMP

In order to reduce trigger voltages, some active CDM ESD clamps have been presented [7]–[9]. However, most of them are not optimized for 3D IC applications. The ground current trigger (GCT) technique [7] and the enhanced initial-on PMOS clamp [8], [9] need additional control signals from different power domains or even from different circuit blocks. In 3D IC applications, once the circuit blocks are placed in different dies, the additional control signals will increase the vertical routing effort, for example, more TSVs have to be inserted for the active CDM ESD clamps, as shown in Fig. 1. In addition, the PMOS clamp [8], [9] cannot be used for high voltage to low voltage (HV-to-LV) interfaces and power down mode applications due to an unwanted on-state of the PMOS clamp. Once the potential of VDD2 (the gate node of the PMOS clamp) is lower than the signal path between two different power domains, the PMOS clamp is turned on which induces huge leakage current during normal circuit operation. In order to solve this unwanted leakage path, a special trigger circuit is also proposed in the following session.

III. TWO PROPOSED DESIGNS

Fig. 2 shows the proposed CDM ESD clamp circuit, Design A, without any external control signals. The main CDM ESD clamp NMOS (Mclamp) is controlled by a one stage inverter (Mp1 and Mn1). The gate terminal of this inverter is connected to the same local VDD2 node.

Under the cross-power domain ESD stress (positive stress from VDD1 to grounded VSS2), the VDD2 is kept floating and the Mp1 can be quickly turned on to trigger the Mclamp. During normal circuit operations, VDD2 is biased at normal VDD potential, the Mp1 and Mclamp are both kept off. However, for HV-to-LV and power down mode applications, Mp1 will be turned on which induces an unwanted Mclamp mis-triggering. Therefore, a special CDM ESD clamp circuit, Design B, is proposed and shown in Fig. 3.

The stacked Mp2 and Mp3 are inserted between the signal path and VDD2. The gate terminal of the inverter is connected to the node, VDD2_E, between Mp2 and Mp3. Under normal circuit operation,

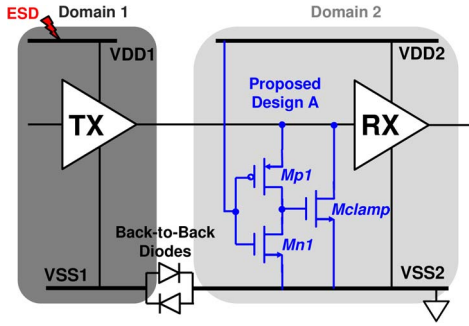


Fig. 2. The proposed Design A which consists of a main ESD clamp NMOS, Mclamp, one stage inverter of Mp1 and Mn1. The inverter is controlled by the VDD2 in the same power domain without any control signal from outside.

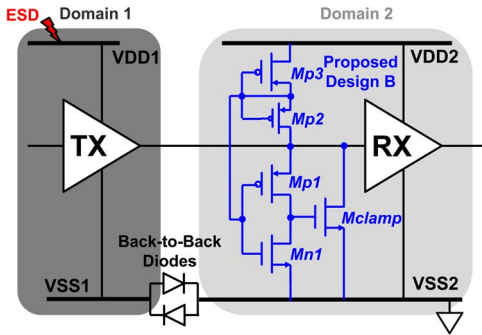


Fig. 3. The proposed Design A which consists of a main ESD clamp NMOS, Mclamp, one stage inverter of Mp1 and Mn1. The inverter is controlled by the VDD2 in the same power domain without any control signal from outside.

TABLE I

THE FUNCTIONAL STATE OF EACH DEVICE IN DESIGN B WHEN VDD2 POTENTIALS ARE HIGH, FLOATING, AND LOW WHICH RESPECTIVELY REFER TO NORMAL OPERATION, ESD STRESS, AND POWER DOWN MODE. THE ARROWS INDICATE THE TRANSIENT SWITCH UNDER THE CORRESPONDING SCENARIOS

VDD2	Mp1	Mp2	Mp3	Mclamp	Mn1
High	Off	Off	On	Off	On
Floating	On→Off	On→Off	Off	On→Off	Off→On
Low	On→Off	On→Off	Off	On→Off	Off→On

the VDD2_E node can be charged to the same potential of VDD2 through the on-state Mp3. On the other hand, Mp2 can charge the VDD2_E node also to high in HV-to-LV and power down mode applications. Mp1 and Mclamp can be switched “OFF” preventing thereby an unwanted mis-triggering. In order to ensure the triggering of Mp1 under cross-power-domain ESD stress, the device size of Mp2 must be smaller than that of Mp1. Before the node of VDD2 is charged up, Mp1 can be kept at “ON” to trigger Mclamp. The functional state of each device in Design B is illustrated in Table I with 3 different scenarios which are the normal operation (VDD2 = “High”), the cross-power-domain ESD stress (VDD2 = “Floating”), and the power down mode (VDD2 = “Low”).

IV. RESULTS AND DISCUSSION

These two proposed designs are implemented in a 0.13 μm 1.2 V fully silicide CMOS technology with a gate oxide thickness of 2.8 nm. They are verified with 2 ns very fast Transmission Line Pulsing (TLP) with 200 ps rise time. The on-wafer HANWA T5000 TLP/vfTLP tester is used to get insights into the ESD device char-

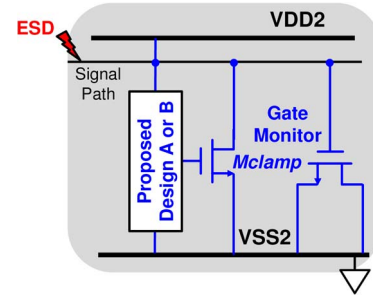


Fig. 4. The illustrated schematic of the test structures used in this work. ESD stressed on the signal path with the grounded VSS2 to simulate the cross-power domain ESD stress.

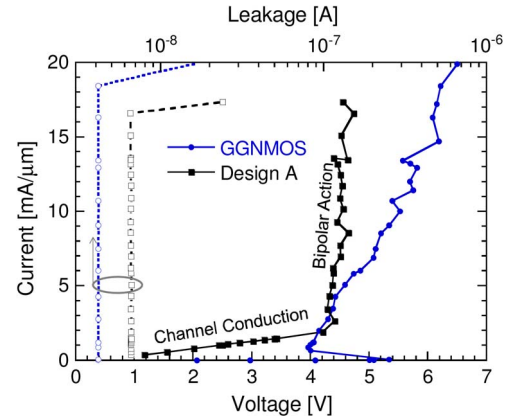


Fig. 5. 2-ns vfTLP IV characteristics of traditional GGNMOS and the proposed Design A. Design A shows two different discharge modes which are channel conduction and parasitic npn bipolar action of Mclamp.

acteristics in the CDM ESD time domain. All of the test structures are designed in parallel with a gate monitor structure to evaluate the efficiency of the gate oxide protection, as shown in Fig. 4. The gate monitor is NMOS capacitance with the gate length and width of 1 μm . After each vfTLP stress, the 1.2 V DC leakage measurement is executed between signal path and VSS2. The VDD2 is biased at 1.2 V during the leakage measurement.

A. Proposed Design A

Fig. 5 shows the vfTLP IV characteristics of the traditional GGNMOS and the proposed Design A.

Compared with the traditional GGNMOS, Design A has a better clamping efficiency. Although the failure current level (I_{t2}) is slightly lower in Design A, it possesses a lower trigger voltage (V_{t1}) of the parasitic npn bipolar and a lower on resistance (R_{on}). Design A shows two current conduction modes. At lower vfTLP stress levels, the current is mainly discharged through the channel of Mclamp. Then, as the vfTLP stress levels increases, the current is discharged through the parasitic npn bipolar of Mclamp. At a current level of 14 $\text{mA}/\mu\text{m}$, the clamping voltage of Design A is around 2 V lower than in a traditional GGNMOS. This can be attributed to a more uniform current distribution along the layout width in the proposed Design A due to the gate driven technique. The gate driven capability of Mclamp is dominated by the W/L ratio of Mp1 and Mn1. With same sizes of Mn1, the larger W/L of Mp1 has larger gate driven capability. Fig. 6 shows the vfTLP IV characteristics of Design A with different W/L ratios of Mp1. Besides a small variation of I_{t2} , the V_{t1} and R_{on} are similar in these three designs. The clamping efficiency is not impacted by the W/L ratio of Mp1 when the W/L ratio of Mp1 is larger than 40.

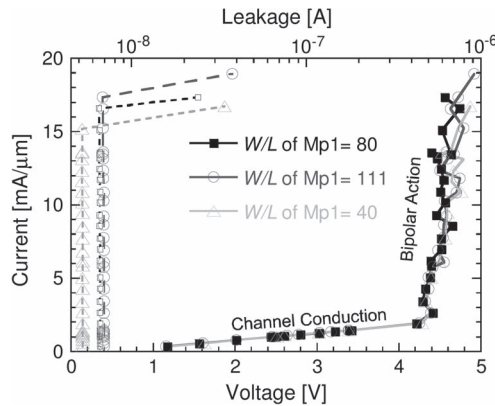


Fig. 6. 2-ns vfTLP IV characteristics of the proposed Design A with different W/L ratios of Mp1. The W/L ratio does not have strong impact on the trigger performance.

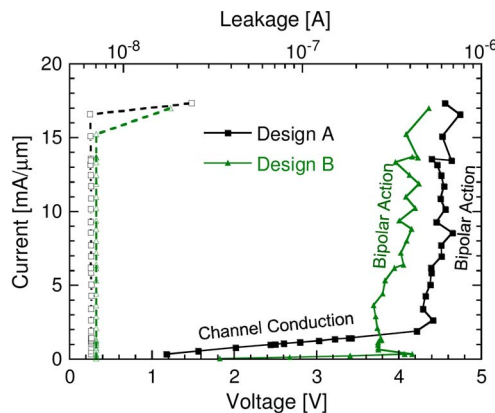


Fig. 7. 2-ns vfTLP IV characteristics of the proposed Design A and B. Design B shows only one discharge mode which is parasitic npn bipolar action of Mclamp.

B. Proposed Design B

Fig. 7 shows the vfTLP IV characteristics of the proposed Design A and B. Design B does not show two current conduction modes. Mclamp does not provide an efficient channel to discharge the current below 4 V. Then, above 4 V, Mclamp directly switches into the parasitic npn bipolar action. The clamping voltage of Design B is

even lower than the one of Design A. The R_{on} of these two designs are rather similar, and also the V_{t1} of the parasitic npn bipolars are both ~ 4 V. The similar R_{on} indicates that the current distribution along the layout width in Design B is as uniform as in Design A. The trigger elements in Design B can well turn-on the parasitic npn bipolar during 2 ns vfTLP stress. However, the holding voltages (V_h) of Design A and Design B have a difference of ~ 0.5 V. The V_h of the traditional GGNMOS, Design A and Design B are ~ 4 V, ~ 4.4 V and ~ 3.8 V, respectively. The difference implies that the different trigger mechanisms can influence the current distribution between channel conduction and parasitic npn bipolar action during 2 ns vfTLP stress.

V. CONCLUSION

In this work, we propose two local CDM ESD clamps for cross-power-domain interfaces in SoC designs or 3D IC applications. The proposed designs, Design A and B, do not need any external control signals which can cause an additional routing effort in real applications. The proposed Design B can be even used in HV-to-LV interfaces or in power-down mode applications. The experimental results show a better clamping efficiency in Design B. It presents the lowest clamping voltage due to the more suitable current distribution.

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